

Date: July 5, 2001
First Use Date 2001 Specifications: November 1, 2002
Revised :November 5, 2007
Revised: July 29, 2009
Revised: September 28, 2009

**DEPARTMENT OF TRANSPORTATION
STATE OF GEORGIA**

SPECIAL PROVISION

Section 300—General Specifications for Base and Subbase Courses

Delete Subsection 300.3.02.H and substitute the following:

H. Fine Grading Equipment

An approved fine grading machine is required for finishing the base and subbase material supporting Portland cement concrete pavement or hot mix asphaltic concrete pavement. Ensure fine grader:

- Is self-propelled and track driven.
- Is capable of trimming and finishing the base and subbase to the specified tolerances utilizing a rotating cutter head in front of a strike-off screed.
- Spans at least one lane width and is controlled automatically by direct contact with a string line or a combination of string line and existing pavement as appropriate.
- Is capable of trimming and finishing base and subbase to the specified tolerances.

Furnish, place, and maintain the necessary string lines to provide continuous line and grade reference to the fine grader control system. GPS controlled equipment can be used in lieu of string lines.

For Graded Aggregate Base construction, a motor grader equipped with GPS controlled equipment can be used as an option for fine grading.

GPS controlled Equipment will include but is not limited to:

1. Ability to read electronic files containing Department supplied data used to design the project.
2. Fixed or movable base station setup on the project to serve as a point of reference for the project. As the project progresses, the movable base station shall be moved for proper system function. If the base station is at a fixed location, radio repeaters will be utilized to ensure the signals from the base station are received throughout the project.
3. A GPS sensor mounted atop a mast affixed to the cutting blade. The masts will be arranged in a dual mast setup with a mast on each end of the blade attachment or in a lone mast setup. The sensor will be able to receive signals from the base station and/or a laser transmitter.
4. A blade position sensor with the ability to detect blade attitude and elevation of the cutting blade and relay this information to the operator. Blade attitude is defined as the orientation of the blade with respect to the three spatial axes in relation to a reference plane.

5. An operator-visible display allowing the operator to visually receive all necessary data in real-time from the GPS system and the cutting blade to properly construct the section to grade. The display will also reflect any changes made by the operator to any operation of the cutting blade.

6. If conformity to the cross sections with the prior listed equipment is unsatisfactory, provide a laser transmitter placed no farther than 800 feet (244 m) from the fine grading equipment. Projects having work progressing at different work sites more than 800 feet (244 m) apart necessitate the use of more than one laser transmitter to ensure accuracy. Select a location for the laser transmitter having a change in elevation of 25 feet (7.62 m) or less from the laser transmitter to the sensor mounted on the cutting blade. If project geography necessitates the use of more than one laser transmitter, the setup of the transmitters will be set to ensure the elevation difference between two consecutive transmitters in an array is not more than 25 feet (7.62 m); and this array cannot exceed a total change in elevation of 100 feet (30.5 m).

Office of Materials & Research